# Globally Nonstationary Multi-Armed Bandits

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Our manuscript is available on <u>arXiv</u> (and this <u>slides</u>)

### Single page summary

- □ *K*-armed (multi-play) multi-armed bandit problem.
- We propose ADR-bandit algorithms that work well in both stationary and globally nonstationary environments.
  - Proposed algorithm: adaptive windows + stationary bandit.
  - Globally nonstationary environments = distributions of all the arms change in a coordinated manner.

#### this paper

١		Stationary	Abrupt	Gradual
	Existing NS-MAB	$\tilde{O}(\sqrt{T})$	$\tilde{O}(\sqrt{T})$	$\tilde{O}(T^{1-d/3})$
	ADR-bandit	$O(\log T/\Delta_{\min})$	$\tilde{O}(\sqrt{T})$ (Under GC)	$\tilde{O}(T^{1-d/3})$ (Under GC)

#### regret bounds of the algorithms

### Agenda

#### Introduction <- Next</p>

- Results on single stream: Total error of ADWIN algorithm
- Results on multi-armed bandits (MABs): Regret bound of ADR-bandit algorithm

## Set up: nonstationary multiple-play MAB

- $\square$   $\mu_{i,t}$ : mean of arm  $i \in \{1, 2, \dots, K\}$  at round t.
- At each round t = 1, 2, ..., T, select L < K arms and receives corresponding rewards  $x_{i,t} \in [0,1]$ 
  - L = 1 (single-play MAB) as a special case
- Goal: maximize rewards by choosing *L* best arms.
- Partial observability (one only knows the reward of selected arms).
- Nonstationarity: Best arms change over time.

$$\square \quad \text{Regret} = \sum_{t} (\max_{I:|I|=L} \mu_{i,t} - \sum_{i \in \text{selected}} \mu_{i,t})$$

### Literature

Literature in non-stationary bandit problems includes:

- Passive algorithms such as sliding windows (fixed size) [Garivier and Moulines 2008, Trovo+2020] and discounting [Kocsis and Szepesvari 2006], and
- active algorithms involves change point detectors such as PHtest [Hartland+2007, Liu+2008], likelihood-ratio test [Besson+2020].
- Lower bound [Garivier and Moulines 2008]: Any non-stationary bandit algorithm (regardless of passive/active) for abrupt changes has at least  $\Omega(\sqrt{T})$  forced exploration.
- Our algorithm is active and avoids forced exploration.

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#### Data mining literature: Stream learning

- A stream is an unknown seq of means  $(\mu_t)_t$ .
  - = arm in our setting
- Stream is stationary if  $\mu_t = \mu$  does not change over time, or
- Abruptly changing if  $\mu_{t+1} \neq \mu_t$  at changepoints  $T_c$ , or
- Gradually changing if  $|\mu_{t+1} \mu_t| \le T^{-d}$  for some constant  $d \le (0,1)$ .



#### Adaptive windowing (ADWIN) [Bifet and Gavalda 2007]

- Q: If we observe all the rewards  $x_1, x_2, x_3, ..., x_{t-1}$ , how accurate one can estimate mean  $\mu_t$  of the current round?
- ADWIN: dynamic control of window W
  - $\hat{\mu}_w$ : Empirical mean based on time steps in  $W = \{s, s + 1, s + 2, ..., t 1\}$ .
- Shrinks *W* when it detects significant gap.



### Analysis of adaptive windowing

- [BG2007] bounds false positive and negative (fp/fn) rates of ADWIN for given t.
  - Cons: fp/fn rates do not directly help bandit analysis. Instead, we bound total error:  $Err(T) = \sum_{t=1}^{T} |\hat{\mu}_W - \mu_t|$

Results in abruptly changing streams:

- Thm 8 (**abrupt**): Total error of ADWIN in an abruptly changing stream with *M* changes is  $\tilde{O}(\sqrt{MT})$ .
- This results is strong, there is NO requirement on the change point size, distance, and the algorithm does NOT need to know *M*.

### Analysis of adaptive windowing

Thm 10 (gradual): Total error of ADWIN in a gradually changing stream is  $\tilde{O}(T^{1-d/3})$ .

> Useful lemma (Lemma 27):

For any  $N \ge |W|$ ,  $|\mu_t - \mu_W| \le 3T^{-d}N + \tilde{O}\left(\frac{1}{\sqrt{N}}\right)$ .





•  $N = T^{2d/3}$  gives the bound of Thm 10.

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#### Scaling bandits [Fouché, Komiyama, Böhm, KDD2019]

- Idea of adaptive window + Thompson sampling was introduced [FKB2019].
  - No analysis for nonstationary bandits, though it empirically performed very well.
- Unlike [FKB2019], this paper gives the regret bound for such algorithms.

### Proposed algorithm: ADR-bandits

- Adaptive resetting (ADR) bandit consists of
- 1. Base bandit algorithm (ex: Thompson sampling, KL-UCB).
- 2. Change point detectors (ADRs) for each of K arms.
- At each round, select arms by using the base bandit algorithm. When one of the ADRs detects a change, reset the entire algorithm.



#### Setting up analysis: Characterize assumptions on base bandit algorithm

The properties of base bandit algorithms:

- 1. (distribution-dependent regret) In a stationary env, it has an  $O(\log T/\Delta)$  regret bound.
- 2. (drift-tolerant regret) In a nonstationary env, it has an  $\tilde{O}(\sqrt{KT} + \epsilon(T))$  regret bound
  - $\epsilon(t) = \text{drift of } \mu_{i,t}.$

3. (monitoring consistency) At least one arms is selected consistently.

We explicitly show an algorithm that has these properties (E-UCB, Algorithm 5)

#### Assumption on the streams: Global changes

- Our algorithm works on stationary and globally changing environments.
- Global changes: All the arms changes in the coordinated manner.
- Similar idea [Mukherjee and Maillard 2019] for abrupt case.



## Main results: Regret bounds

Under the assumptions on the previous pages:

Stationary case:

Theorem 20: In a stationary env, the regret of ADR-

bandit is  $O\left(\frac{\log T}{\Delta}\right)$ .

Non-stationary cases:

disclaimer: requires detectability condition

Theorem 22: In an env with globally abrupt changes, the regret of ADR-bandit is  $O(\sqrt{MKT})$ .

Theorem 24: In an env with globally gradual changes,

the regret of ADR-bandit is  $O\left(\left(\sqrt{LK}\right)T^{1-\frac{d}{3}}\right)$ .

#### Experimental results



More results on the paper

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	Stationary MAB	$O(\log T/\Delta_{\min})$	O(T)	O(T)

#### regret bounds of the algorithms

# Future works (last slide)

Further characterization of non-stationary bandits that extend stationary bandits: There are some NON-global changes that stationary bandit algorithm can deal with.

